

**AMENDMENTS TO THE CLAIMS**

Claims 1-3 (Cancelled)

4. (Currently Amended) A method for the autonomic management of autonomic systems, the method comprising the steps of:

monitoring a managed system and recommending a course of action to be performed in said managed system;

determining whether said recommended course of action has been performed by an administrator and responsive to said determination, further determining whether an outcome from said course of action comports with a predicted outcome;

changing a point count responsive to a further determination that said outcome from said course of action comports with said predicted outcome, and oppositely changing said point count responsive to a further determination that said outcome from said course of action does not ~~comports~~ comport with said predicted outcome; and,

when said point count crosses a threshold value, transitioning management of said managed system to an adaptive component.

5. (Original) The method of claim 4, further comprising the step of when said point count re-crosses said threshold value in a direction opposite a direction which gave rise to said transitioning step, returning management of said managed system to a predictive component.

6. (Currently Amended) The method of claim 4, wherein said transitioning step comprises the steps of:

detecting a crossing of said threshold value in a changing of said point count;  
smoothing changes in said point count ~~to avoid a hysteresis condition~~; and,  
permitting said transition step only after said step of smoothing changes when said hysteresis condition has been avoided.

7. (Original) The method of claim 5, further comprising the step of requesting permission from an administrator prior to returning management of said managed system to said predictive component.

8. (Original) The method of claim 4, further comprising the step of forbidding a transition to said adaptive component by setting said threshold value to a de facto infinite value.

9. (Currently Amended) A machine readable storage having stored thereon a computer program for the autonomic management of autonomic systems, the computer program comprising a routine set of instructions for causing the machine to perform the steps of:

monitoring a managed system and recommending a course of action to be performed in said managed system;

determining whether said recommended course of action has been performed by an administrator and responsive to said determination, further determining whether an outcome from said course of action comports with a predicted outcome;

changing a point count responsive to a further determination that said outcome from said course of action comports with said predicted outcome, and oppositely changing said point count responsive to a further determination that said outcome from said course of action does not ~~comports~~ comport with said predicted outcome; and,

when said point count crosses a threshold value, transitioning management of said managed system to an adaptive component.

10. (Original) The machine readable storage of claim 9, further comprising the step of when said point count re-crosses said threshold value in a direction opposite a direction which gave rise to said transitioning step, returning management of said managed system to a predictive component.

11. (Currently Amended) The machine readable storage of claim 9, wherein said transitioning step comprises the steps of:

detecting a crossing of said threshold value in a changing of said point count;  
smoothing changes in said point count ~~to avoid a hysteresis condition~~; and,  
permitting said transition step only after said step of smoothing changes when said hysteresis condition has been avoided.

12. (Original) The machine readable storage of claim 10, further comprising the step of requesting permission from an administrator prior to returning management of said managed system to said predictive component.

13. (Original) The machine readable storage of claim 9, further comprising the step of forbidding a transition to said adaptive component by setting said threshold value to a de facto infinite value.